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JU

Data Sheet 70.3580

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JUMO DICON 401/501 **Universal profile controllers Universal profile generators**

Brief description

The series of universal, freely configurable profile controllers/generators is available in the formats 96mm x 96mm and 96mm x 48mm (portrait and landscape format).

The instruments feature two 4-digit 7-segment displays, five or eight LEDs for indicating the switching status and operating modes, an 8-digit matrix display, as well as six keys for operation and configuration.

The user has flexibility in assigning the slots of the profile controller according to the block structure

10 profile programs with up to 100 segments can be programmed; a total of 100 segments is available.

Additional functions include self-optimisation, parameter set switching, a real-time clock, up to 8 limit comparators and a maximum of eight operating contacts.

Linearisations for conventional transducers are stored in the memory; furthermore, a customized linearisation table can be programmed.

The profile controllers can be adapted to a variety of tasks with the aid of a maths module. The instruments can be integrated into a data network via a serial interface, or they can be expanded through an external relay module.

A setup program with a program editor is available for easy configuration from a PC. The electrical connection is at the rear by screw terminals.





JUMO DICON 501 Type 703580/0...



JUMO DICON 401 Type 703585/1 ...



JUMO DICON 401 Type 703585/2...

Features

- Switchable displays
- Text or bar graph display
- 8 limit comparators
- 2 parameter sets
- Maths and logic module
- 8 operating contacts
- Real-time clock
- Setup program with program editor and JUMO start-up software for Windows[®] 95/98/NT4.0
- Approved to DIN 3440 (for Type 703580)
- UL approval
- GL approval applied for

Profile controller

10 profile programs with up to 100 segments can be programmed. A total of 100 segments is programmable. In addition, eight operating contacts can be assigned to the corresponding program segments.

A profile program can be started manually from the keys (on the instrument or externally), or by programming the start conditions. When programming the start conditions, the time can be set either by selecting a start delay, or by programming a weekday and time. Furthermore, it is possible to program a weekly profile with 10 entries via the setup program.



Profile programs consist of a series of segments with definable segment setpoints. The individual segment setpoints are connected either by ramps or by step functions. At each segment, the status of the eight operating contacts can be modified.

In addition, each segment can have assigned to it one of the two programmable parameter sets, as well as an upper and a lower limit (tolerance band) for monitoring the process value.

Continuous loops can be set up through programmable repeat cycles. Segments are defined by the segment setpoint and segment time, or the ramp slope (gradient). Through the integral program editor it is possible to create segments from the keys, as well as to edit, copy or delete them.



Customized linearisation

In addition to the linearisation for the usual transducers, a customer-specific linearisation can be created.

Programming is carried out via the setup program, in the form of a table of values.

Maths and logic module (option)

The maths module permits integrating e.g. setpoints, control outputs and the measured values of the analogue inputs into a mathematical formula.

The logic module can be used to create logic links between logic inputs, limit comparators and operating contacts, for example.

Two formulae can be entered via the setup program for each of the two modules. The results of the calculation can then be produced via the outputs or used for internal purposes.

There is an additional possibility of implementing difference, ratio and humidity control through established standard formulae.

Configurable displays

Any process variable can be visualised on the 7-segment displays and the dot-matrix display.

It is possible to switch between two displays either from the keys, or automatically after an adjustable interval.

Setup program (accessory)

The setup program for instrument configuration is available in English, German and French. A PC can be used to create and edit data sets, transfer them to the controller, or read them out of the instrument. The data sets are stored and managed.

Carlow Control Co	Setup program DICON 40.	и/50x - [Setup2 - altered -]	
Cale of a model Cole	Bie Edt Data transfer b;	glass Window Jolo	_0
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htermentanen werken Sen den Sen den	File info head	Profile controller	
Envision Hardware + e SackSS22 indice SackSS22 indice SackSS22 indice SackSS22 indice Cardio Sacks Sack Sack SackSS22 indice Cardio Sacks Sack SackSS22 indice SackSS22 indice Sack	Instrument name: Instrument SW-version: VDN: Short info: Programmer: Type code: Job:	Function Functi	
And a second sec	Extra info Hardware + e Version: RS495/RS422 interface: Stort: Stort:	Programming Progr	
Index Concel	Slot3 Slot5 Slot5 Slot5 Input 1: Input 2 Input 3	Function control Controls Controls Control Con	
fataainta:	Input 4: extra Codes: Maths is not enabled	OK Cancel	
	Cotnointo:		

With the aid of the program editor, which is integrated into the setup program, profile programs can easily be created, edited and transferred.

Self-optimisation

The standard specification includes an auto-tuning facility which permits the user to adjust the controller to the process without any knowledge of control engineering.

JUMO Start-up software

The JUMO start-up software is an integral part of the setup program and is available for conveniently adapting the controller to the process.

Different process variables (e. g. setpoint, process value, control deviation, signals from the controller outputs) can be displayed graphically. The controller parameters can be altered and transferred to the controller via the setup or RS422/485 interfaces



Text display

Customer texts can be assigned to the functions of the logic inputs, the limit comparators, the logic outputs of the logic module and the operating contacts. It is also possible to designate profile program names.

Depending on the status of the function or the configuration of the displays, a programmed text (8 characters max.) is shown on the matrix display.

The customer texts and the program names can only be set up with the aid of the setup program.

PROFIBUS-DP (option)

The controller can be integrated into a fieldbus system to the PROFIBUS-DP standard, via the PROFIBUS-DP interface. This PROFIBUS variant has been designed specifically for the communication between automation systems and decentralised peripheral instruments at the field level, and is speed-optimised.

The data are transmitted serially in accordance with the RS485 standard.

Using the project design tool included in the delivery (GSD-generator; GSD = instrument master data), a standardised GSD file is created that serves to integrate the controller into the fieldbus system, through selection of the controller data.

RS422/RS485 interface (option)

The serial interface is available for communication with higher-level systems. MODbus/Jbus are used as transmission protocols.

External relay module ER8 (accessory)

The controller can be expanded by eight relay outputs through the external relay module ER8. Operation is via the RS422/RS485 interface.

The setup program is necessary for configuring the ER8, which can be mounted on a standard DIN rail.

Functions of the logic inputs

- Programming inhibit
- Profile program start/stop/cancel
- Profile program selection
- Fast forward
- Segment change - Start/cancel self-optimisation
- Setpoint switching
- Process value switching
- Parameter set switching
- Key/level inhibit _
- Text display
- All displays off
- Auto/manual changeover

Functions of the outputs

- Analogue input variables
- Mathematics
- Process value
- Setpoint
- Control deviation
- Control output
- Controller outputs
- Limit comparators
- Operating contacts
- Logic inputs
- Logic
- Profile-program end signal
- Tolerance band signal
- Manual mode signal

Operation, parameterization, configuration

Operation, as well as setting the controller parameters and configuration, are arranged at different levels.

Operating level

Different process variables (measurements of the analogue inputs, program times...) can be indicated here.

Profile program start

The conditions for the start of the program are defined here.

Profile program editor

Here, the programs are set up from the keys and edited.

Parameter level

The controller parameters are set here.

Configuration level 1

The basic functions of the instrument, such as restart, profile program end time, are set at this level.

Configuration level 2

The hardware and software codes which correspond to the controller version are indicated here.





Displays and controls



Isolation



Profile controller (extract from configuration level 1)

Parameters	Selection/Value range	Description
Function	Profile controller Profile generator	The instrument can be operated as profile controller or profile generator.
Restart	Profile program stop Continue Hold Continue at deviation <x% Continue at process value</x% 	Response of the controller on a supply failure.
Profile program start	Start at profile program start Start at process value	Start conditions for the start of profile programs.Program start:Program starts with the programmed setpoint of the first segment (A01)Start at PV:The present process value is accepted as the first setpoint; the program starts at the corresponding segment
Setpoint input	Setpoint ramp Setpoint step	Setpoint ramp: Setpoint step: w A01 A02 A01 A02 t t t
Time/gradient	Time Gradient	Types of program entry. Time: segment setpoint/segment time Gradient: segment setpoint/gradient
Function control	Generator control Operating contact 1 Operating contact 8	Controller and limit comparators 1 – 8 can be switched off individually during the program run. Generator control: Operating contact 1–8: Controller or limit comparators are active during the program run Operating contact 1–8: Controller or limit comparators are only active, when the corresponding operating contact is in the "ON" status
Process value deviation	0 — 100 digit	Parameter for "Continue at deviation < x%"
Profile program end time	-1 — 9999 sec	Duration of the program end signal (for outputs); -1= infinite

Parameter level

The table lists all the parameters and their meaning. Depending on the controller type, certain parameters are irrelevant or not applicable. Two parameter sets can be stored for specific applications.

$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Parameters	Display	Value range	factory-set	Meaning
Structure 2P, I, PD, PI, PIDPIDthe case of a double-setpoint controllerProportional bandXp10 – 9999 digit0 digitSize of the proportional band At Xp = 0 the controller structure is not effective!Derivative timeTv10 – 9999 sec80 secInfluences the differential component of the controller output signalReset timeTn10 – 9999 sec350 secInfluences the integral component of the controller output signalSwitching cycle timeCy10 – 9999 sec20 secFor a switching output, the cycle time should be selected so that the energy sup- ply to the process is virtually continuous while, at the same time, not overloading the switching differentialContact spacingXsh0 – 9999 digit1 digitDifferential for switching controllers, modulating controllers and proportional controllers, modulating controllers and proportional controllers within integral actuator driverSwitching differentialXd10 – 999 digit1 digitDifferential for switching controllers in for Xp = 0Structure timeTT5 – 3000 sec60 secUtilised stroke time of the control valve on modulating controllers and proportional controllers and proportional controllers with integral actuator driverWorking pointY0-100 to +100%0%Output on P and PD controllers (y = Y0 at x = w).Output limitY10 – 100%100%Maximum output limitMinimum relayTk10 – 60 sec0 secLimitation of the switching frequency on output limit	Controller structure	Structure 1	P, I, PD, PI, PID	PID	Structure 2 refers to the second output in
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		Structure 2	P, I, PD, PI, PID	PID	the case of a double-setpoint controller
Xp20 - 9999 digit0 digitAt Xp =0 the controller structure is not effective!Derivative timeTv10 - 9999 sec80 secInfluences the differential component of the controller output signalReset timeTn10 - 9999 sec350 secInfluences the integral component of the controller output signalSwitching cycle timeCy10 - 9999 sec20 secFor a switching output, the cycle time switching output, the cycle time switching output, the cycle time switching output, the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh0 - 9999 digit1 digitSpacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driverSwitching differentialXd10 - 9999 digit1 digitDifferential for switching controllers and proportional controllers and proportional controllers and proportional controllers with integral actuator driverSwitching pointY0-100 to +100%0%Output on P and PD controllers (y = w).Uutput limitingY10 - 100 to +100 %-100 %Maximum output limitMinimum relayTk10 - 60 sec0 secLimitation of the switching frequency on other sectors	Proportional band	Xp1	0 — 9999 digit	0 digit	Size of the proportional band
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		Xp2	0 — 9999 digit	0 digit	At Xp =0 the controller structure is not effective!
Tv20 - 9999 sec80 secController output signalReset timeTn10 - 9999 sec350 secInfluences the integral component of the controller output signalSwitching cycle timeCy10 - 9999 sec20 secFor a switching output, the cycle time should be selected so that the energy sup- ply to the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh0 - 9999 sec0 digitSpacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driverSwitching differentialXd10 - 999 digit1 digitDifferential for switching controllers for Xp = 0Stroke timeTT5 - 3000 sec60 secUtilised stroke time of the control valve on modulating controllers and proportional controllers and proporti	Derivative time	Tv1	0 — 9999 sec	80 sec	Influences the differential component of the
Reset timeTn10 - 9999 sec350 secInfluences the integral component of the controller output signalSwitching cycle timeCy10 - 9999 sec20 secFor a switching output, the cycle time should be selected so that the energy sup- ply to the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh0 - 9999 sec0 digitSpacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driverSwitching differentialXd10 - 999 digit1 digitDifferential for switching controllers for Xp = 0Stroke timeTT5 - 3000 sec60 secUtilised stroke time of the control valve on modulating controllers with integral actuator driverWorking pointY0-100 to +100%0%Output on P and PD controllers (y = Y0 at x = w).Output limitingY10 - 60 sec0 secLimitation of the switching frequency on output limitMinimum relayTk10 - 60 sec0 secLimitation of the switching frequency on output limit		Tv2	0 — 9999 sec	80 sec	controller output signal
Tn20 - 9999 sec350 seccontroller output signalSwitching cycle timeCy10 - 9999 sec20 secFor a switching output, the cycle time should be selected so that the energy sup- ply to the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh0 - 9999 sec0 digitSpacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driverSwitching differentialXd10 - 999 digit1 digitDifferential for switching controllers for Xp = 0Stroke timeTT5 - 3000 sec60 secUtilised stroke time of the control valve on modulating controllers with integral actuator driverWorking pointY0-100 to +100%0%Output on P and PD controllers (y = Y0 at x = w).Output limitingY10 - 100%100%Maximum output limitMinimum relayTk10 - 60 sec0 secLimitation of the switching frequency on mutation art stroke	Reset time	Tn1	0 — 9999 sec	350 sec	Influences the integral component of the
Switching cycle time $Cy1$ $0 - 9999 \sec$ $20 \sec$ For a switching output, the cycle time should be selected so that the energy sup- ply to the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh $0 - 9999 \sec$ 0 digitSpacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers, modulating controllers with integral actuator driverSwitching differentialXd1 $0 - 9999$ digit1 digitDifferential for switching controllers for Xp = 0Stroke timeTT $5 - 3000 \sec$ $60 \sec$ Utilised stroke time of the control valve on modulating controllers with integral actuator driverWorking pointY0 $-100 \text{ to } +100\%$ 0% Output on P and PD controllers (y = Y0 at x = w).Output limitingY1 $0 - 100\%$ 100% Maximum output limitMinimum relayTk1 $0 - 60 \sec$ $0 \sec$ Limitation of the switching frequency on owitables on struction of the switching frequency on ewitables on the switching frequency on		Tn2	0 — 9999 sec	350 sec	controller output signal
Cy2 $0 - 9999 \text{ sec}$ 20 sec should be selected so that the energy supply to the process is virtually continuous while, at the same time, not overloading the switching devices.Contact spacingXsh $0 - 9999 \text{ sec}$ 0 digit Spacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driverSwitching differentialXd1 $0 - 999 \text{ digit}$ 1 digitDifferential for switching controllers for Xp = 0Stroke timeTT $5 - 3000 \text{ sec}$ 60 secUtilised stroke time of the control valve on modulating controllers with integral actuator driverWorking pointY0-100 to +100%0%Output on P and PD controllers (y = Y0 at x = w).Output limitingY1 $0 - 60 \text{ sec}$ 0 secLimitation of the switching frequency on switching neutring (y = N0 at x = w).Minimum relayTk1 $0 - 60 \text{ sec}$ 0 secLimitation of the switching frequency on switching neutring switching neutring the switching frequency on switching requency on switching neutring	Switching cycle time	Cy1	0 — 9999 sec	20 sec	For a switching output, the cycle time
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Switching differential Switching differentialXd10 - 999 digit1 digitDifferential for switching controllers for Xp = 0Stroke timeTT $5 - 3000 \sec$ $60 \sec$ Utilised stroke time of the control valve on modulating controllers and proportional controllers with integral actuator driverWorking pointY0 $-100 \text{ to } +100\%$ 0% Output on P and PD controllers (y = Y0 at x = w).Output limitingY1 $0 - 100\%$ 100% Maximum output limit Y2Minimum relayTk1 $0 - 60 \sec$ $0 \sec$ Limitation of the switching frequency on put strates	Contact spacing	Xsh	0 — 9999 sec	0 digit	Spacing between the two control contacts for double-setpoint controllers, modulating controllers and proportional controllers with integral actuator driver
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Working pointY0-100 to +100%0%Output on P and PD controllers $(y = Y0 \text{ at } x = w).$ Output limitingY10 - 100%100%Maximum output limitY2-100 to +100%-100%Minimum output limitMinimum relayTk10 - 60 sec0 secLimitation of the switching frequency on switching output to the text	Stroke time	ТТ	5 — 3000 sec	60 sec	Utilised stroke time of the control valve on modulating controllers and proportional controllers with integral actuator driver
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Working point	Y0	-100 to +100%	0%	Output on P and PD controllers $(y = Y0 \text{ at } x = w).$
Y2 -100 to +100 % -100% Minimum output limit Minimum relay Tk1 0 - 60 sec 0 sec Limitation of the switching frequency on switching output is	Output limiting	Y1	0 - 100%	100%	Maximum output limit
Minimum relay Tk1 0 - 60 sec 0 sec Limitation of the switching frequency on switching outputs		Y2	-100 to +100 %	-100%	Minimum output limit
()NI time	Minimum relay	Tk1	0 - 60 sec	0 sec	Limitation of the switching frequency on
Tk2 $0 - 60 \text{ sec}$ 0 sec	ON time	Tk2	0 - 60 sec	0 sec	switching outputs

Technical data

Thermocouple input

Designation		Range	Meas. accuracy	Ambient temperature error
Fe-Con L		-200 +900°C	≤ 0.25%	100 ppm per °C
Fe-Con J	EN 60 584	-210 +1200°C	≤0.25%	100 ppm per °C
Cu-Con U		-200 +600°C	≤ 0.25%	100 ppm per °C
Cu-Con T	EN 60 584	-270 +400°C	≤0.25%	100 ppm per °C
NiCr-Ni K	EN 60 584	-270 +1372°C	≤ 0.25%	100 ppm per °C
NiCr-Con E	EN 60 584	-270 +1000°C	≤0.25%	100 ppm per °C
NiCrSi-NiSi N	EN 60 584	-270 +1300°C	≤ 0.25%	100 ppm per °C
Pt10Rh-Pt S	EN 60 584	-50 +1768°C	≤0.25%	100 ppm per °C
Pt13Rh-Pt R	EN 60 584	-50 +1768°C	≤ 0.25%	100 ppm per °C
Pt30Rh-Pt6Rh B	EN 60 584	0 — 1820°C	≤ 0.25%	100 ppm per °C
W5Re-W26Re		0 – 2320°C	≤ 0.25%	100 ppm per °C
W3Re-W25Re		0 — 2400°C	≤ 0.25%	100 ppm per °C
Cold junction		Pt100 internal, ex	ternal or constant	

Resistance thermometer input

Designation		Connection type	Range	9	Meas. accuracy	Ambient temperature error
Pt100	EN 60 751	2-wire/3-wire	-200	+850°C	≤0.05%	50 ppm per °C
Pt 50,500, 1000	EN 60 751	2-wire/3-wire	-200	+850°C	≤0.1%	50 ppm per °C
KTY11-6		2-wire	-50	+150°C	≤1.0%	50 ppm per °C
Cu50		2-wire/3-wire	-50	+200°C	≤0.1%	50 ppm per °C
Ni100	DIN 43 760	2-wire/3-wire	-60	+250°C	≤0.05%	50 ppm per °C
PTK9		2-wire	lithium	n-chloride se	nsor	
Sensor lead resista	nce		max. 30 Ω	per conduc	tor in 2-/3-wire circuit	
Measuring current				250	μA	
Lead compensation	1	not required for 3-wire software by a process v	circuit. For alue corre	2-wire circu ction.	iit, lead compensatior	n can be provided in the

Standard signal input

Designation	Range	Meas. accuracy	Ambient temperature error
Voltage	$\begin{array}{lll} 0 & - & 10 \text{V}, & \text{input resistance } R_E > 100 \text{k}\Omega \\ -10 \ \text{to} + 10 \text{V}, & \text{input resistance } R_E > 100 \text{k}\Omega \\ 1 \ \text{to} + & 1 \text{V}, & \text{input resistance } R_E > 100 \text{k}\Omega \\ 0 \ \text{to} + & 1 \text{V}, & \text{input resistance } R_E > 100 \text{k}\Omega \\ 0 \ - & 100 \ \text{mV}, \text{input resistance } R_E > 100 \text{k}\Omega \\ - & 100 \ \text{to} + & 100 \ \text{mV}, \text{input resistance } R_E > 100 \text{k}\Omega \\ \end{array}$	≤0.05% ≤0.05% ≤0.05% ≤0.05% ≤0.05% ≤0.05%	100 ppm per °C 100 ppm per °C
Current	$4 - 20$ mA, voltage drop $\leq 1V$ 0 - 20 mA, voltage drop $\leq 1V$	≤0.05% ≤0.05%	100 ppm per °C 100 ppm per °C
Potentiometer	0 — 50mA AC 100 Ω min., 10k Ω max.	≤1%	100 ppm per °C

Measurement circuit monitoring¹

Transducer	Over/underrange	Probe/lead short-circuit ¹	Probe/lead break
Thermocouple	•	-	•
Resistance thermometer	•	•	•
Voltage 2 - 10V 0 - 10V	•	•	•
Current 4 – 20mA 0 – 20mA	•	•	•

•= recognised -= not recognised

1. In the event of an error, the outputs move to defined states (0%, 100%, -100% configurable).

Standard version

Outputs

Relay contact rating contact life		changeover contact 3A at 250VAC resistive load 150 000 operations at rated lo	ad
Logic current limiting	0/5 V 20 mA	or	0/22V 30mA
Solid-state relay contact rating		1A at 230V	
Voltage output signals load resistance		-10 to +10V/0 — 10V/2 — 10 R _{load} 500 Ω min.	V
Current output signals load resistance	-2	20 to +20mA/0 — 20mA/4 — 2 R _{load} 450 Ω max.	20mA
Supply for 2-wire transmitter voltage current		22V 30mA	

Controller

Controller type	single setpoint-controller,	
	double setpoint-controller, modulating controller, proportional controller,	
	proportional controller with integral actuator driver	
Controller structures	P/PD/PI/PID	
A/D converter	resolution better than 15 bit	
Sampling time	210msec	

Electrical data

Supply (switched mode power supply)	110 — 240V AC -15/+10% 48 — 63Hz
	20 — 30V AC/DC, 48 — 63Hz
Test voltages (type test)	to EN 61 010, Part 1
	overvoltage category II, pollution degree 2
Power consumption	10 VA max. for Type 703580
	7 VA max. for Type 703585
Data backup	EEPROM
Electrical connection	At the rear via screw terminals,
	conductor cross-section up to 2.5 mm ²
	and core-end sleeve (length: 10mm)
Electromagnetic compatibility	EN 50 081-1, EN 50 082-2, NAMUR recommendation NE21
Safety standards	to EN 61 730-1 for Type 703580
	to EN 61 010-1 for Type 703585

Housing

Housing type	plastic h	ousing for panel mounting to D	IN 43 700		
Dimensions in mm (for Type)	703585/1 703585/2 703580/0				
Bezel	48 x 96 (portrait)	96 x 48 (landscape)	96 x 96		
Depth behind panel	130	130	130		
Panel cut-out	45 ^{+0.6} x 92 ^{+0.8}	92 ^{+0.8} x 45 ^{+0.6}	92 ^{+0.8} x 92 ^{+0.8}		
Ambient/storage temperature range		-5 to 50°C / -40 to +70°C			
Climatic conditions	rel. humidity, no	t exceeding 90% annual mean,	no condensation		
Operating position		any			
Protection	to EN 60 529,				
	front IP65, rear IP20				
Weight (fully fitted)	approx. 420g	approx. 420g	approx. 730g		

Standard version

Interface

Connection diagrams

Type 703580







(option)





Logic inputs 5+6 (Slot 2)

Logic inputs 7+8 (Slot 3)

Logic inputs 3+4 (Slot 1)

Potentiometer

Heater current 0—50mA AC

Analogue input 1

Type 703585/1... (portrait format) and Type 703585/2... (landscape format) Interface 0 Ø1∏ PROFIBUS DP 02 Ц **⊡**1⊘ Ø Π TE ⊠¹⊘ ∏ı⊘ +5 V 03 Д \oslash Ы L1(L+) ∏2⊘ Ы 20 1∐2⊘ 20 mA A B GND Ø₄∐ **∏**₃⊘ ∏₃⊘ \oslash N(L-) ∏₃⊚ Ш Ø5∐ ⁽) 6 0 Ø '© \otimes \otimes \otimes MM Н RS485/ER8 П 6 6 į 6 RxD/RxD/ TxD TxD GND (+) (-) 1 HTEL1N AC \sim 110 - 240V RS422 AC/DC ł RxD RxD TxD TxD GND \sim (--) (+) (+) (-) 20-30V Mains supply 1 2 3 4 5 Output 3 Output 2 Output 1 (Slot 3) (Slot 2) (Slot 1) -20/0/4-20mA -20/0/4-20mA -20/0/4—20mA i i i -10/0/2-10V -10/0/2-10V -10/0/2-10V u u u 230V/1A 230V/1A 230V/1A ₿ -∦ ₩ ₿ 5V(22V)/30mA* 5V(22V)/30mA* 5V(22V)/30mA* П П П 230V/3A 230V/3A 230V/3A 54 34 6¹1 4 1 2 3 2 3 2 3 2 3 8 9 10 11 1 4 7 BE7 BE5 BE3 BE1 Thermocouples Resistance thermometer (3-wire) k ti∂ tito tito b BE BE4 BE6 BE2 Resistance thermometer (2-wire) Logic inputs 7+8 ′ื¦อ¦ ₿₦₀ Logic inputs 5+6 Logic inputs 3+4 (Slot 3) (Slot 2) (Slot 1) * Supply for 2-wire transmitter (22V) Voltage 0/2-10V Current 0/4—20mA

Logic inputs 1+2

Analogue input 2

5.00/00367439

Dimensions

Type 703580/0...







panel cut-out to DIN 43 700



Type 703585/2... (landscape format)



External relay module ER8

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Type 703585/1... (portrait format)





panel cut-out to DIN 43 700





Edge-to-edge mounting Minimum distances of panel cut-outs											
Туре	horizontal	vertical									
without setup plug:											
703580/0	11mm	30mm									
703585/1 (portrait)	11mm	30mm									
703585/2 (landscape)	30mm	11mm									
with setup plug:											
703580/0	11mm	65mm									
703585/1 (portrait)	11mm	65mm									
703585/2 (landscape)	65mm	11mm									

Accessories

External relay module ER8*
Supply 93 – 263V AC
Sales No. 70/00325805
External relay module ER8*
Supply 20 – 53V DC/AC
Sales No. 70/00325806
PC interface for setup program
Sales No. 70/00301315
Setup program with program editor for
Windows [®] 95/98 and NT4.0
Hardware requirements:
- PC-486DX-2-100
- 16 Mbyte RAM
- 15 Mbyte available on hard disk
- CD-ROM
- 1 free serial interface

* The RS422/485 interface is required for operating the external relay module!

Ordering details

	Basic type																												
703580	DICON 501: Universal profile controller/profile generator in 96mm x 96mm format																												
703585	JIMO DIC	ON 4	401: Universal profile controller/profile generator in 96mm x 48mm and 48mm x 96mm formats																										
<u> </u>																													
				Basic type extensions																									
					Form	at																							
		0			96mm	n x 96	3mr	m																					
		1			48mm	n x 96	3mr	n por	trait	forr	nat																		
		2			96mm	n x 48	3 mr	n lan	dsca	pe ·	form	nat																	
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									2	2	2	2	2	2	Solid-	state	ate relay 230V 1A												
									3	3	3	3	3	3	Logic	0/5V	,												
									4	4	4	4	4	4	Logic	0/22	V												
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																	Sup	ply											
															2	3	3 110 - 240V -15/+10% AC 48 - 63Hz												
															2	5	20	20 - 30 VAC/DC $48 - 63 Hz$											
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Stock ver	rsions																												

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